## DR. BABASAHEB AMBEDKAR TECHNOLOGICAL UNIVERSITY, LONERE

**Supplementary Winter Examination – 2024** 

/Mech. Engg. (Sandwich)

Course: B.Tech. Branch: Mechanical Engineering Semester: VII

Subject Code & Name: BTMEC702, CAD/CAM

Max-Marks: 60 Date:07/02/2025 Duration: 3√Hr.

## Instructions to the Students:

- 1. Each question carries 12 marks.
- 2. Question No. 1 will be compulsory and include objective-type questions.
- 3. Candidates are required to attempt any four questions from Question No. 2 to Question No. 6.
- 4. The level of question/expected answer as per OBE or the Course Outcome (CO) on which the question is based is mentioned in ( ) in front of the question.
- 5. Use of non-programmable scientific calculators is allowed.
- 6. Assume suitable data wherever necessary and mention it clearly.

	6. <i>F</i>	Assume suitable d	ata wherever nec	essary and mentio	n it	ciearly.		1
							(Level	Marks
							/CO)	
Q.	1	Objective type of	questions. (Comp	ulsory Question)				12
1	~	To view portion of a image enclosed in a rectangular region is called					CO-01	1
	7.3	a. View port	b. Windowing	c. Raster scan	d.	Stroke writing		73
2	0361	To display different portions of the drawing in different region of the					CO-01	361
		screen is called						Ö
	51	a. View port	b. Windowing	c. Raster scan	d. 9	Stroke writing		21
3		In geometric modelling Solid model contains					CO-2	1
		a. Geometrical data	b. Topological information	c. Geometrical data & Topologica information	ы I	d. Topographical information		
4		In geometric modeling wire frame and surface models contains						1
	73	a. Geometrical data	b. Topological information	c. Geometrical data & Topologic information	cal	d. Topographical information		73
5	31	Easiest and most advanced method of geometric modelling is				CO-2	<del>1</del> 9	
	036	a. Solid modelling	b. Wire frame modelling	c. Surface modeling		d. None of these		036
6	1	Primitives are combined by mathematical set of Boolean operations in					CO-03	11
	ΓĊ	a. Constructive Solid modeling	b. Destructive Solid modeling	c. Boundary representation		d. Sweeping		N
7		A surface model is generated by using wire frame entities - plane surface, ruled surface, tabulated surface & surface of revolution is known as					CO-03	1
		a. Analytical entities	b. Synthetic entities	c. Destructive Solid Geometry		d. Solid modelling		

8		Bezier surface a	llows			CO-03	1
		a. Local	b. Global contro	c. Both local and	d. None of these		
		control		global control			
9		Elements of Nur	merical Control sy	stem are	<u> </u>	CO-04	1
		a. Program of		c. Processing	d. All the above		
10	9	instructions		equipment		60.05	9
10	17	; in manuai part p ' is	program preparat	ory code for "rapid mo	vement line path	CO-05	1
	36	a.G00	b. G01	c. G60	d. G71		36
11	10	In manual part p	program code for	auxiliary function "pro	gram end with	CO-05	1
	51	rewind" is					51
		a. M30	b. M01	c. M03	d. M02		
12		In APT programi	ming the surface	which guide the side o	f the cutter is	CO-06	1
		known as					
		a. Drive surface	b. Part surfac	ce c. Check surface	d. Fillet surface	-	
Q. 2	200	Solve the follow	ina	~			00
	N.	Solve the lonow	nig.	(,)			(12
A)	317			ntrol devices used as C	CAD input device.	CO-01	6
A) B)	3617	Explain minimur	m three cursor co	ntrol devices used as 0 0, 20), B (80, 20), and	·	CO-01	6-
	103617	Explain minimur	m three cursor co		C (20, 80) is to be		<u>/</u> 4960
	5103617	Explain minimur  A triangle ABC v  scaled by factor	m three cursor co with vertices A (2 r of 0.5 about a	0, 20), <b>B</b> (80, 20), and	C (20, 80) is to be ermine composite		6-
	5103617	Explain minimur  A triangle ABC v  scaled by factor	m three cursor co with vertices A (2 r of 0.5 about a	0, 20), B (80, 20), and point X (40, 40). Det	C (20, 80) is to be ermine composite		<u>/</u> 4960
	5103617	Explain minimur  A triangle ABC v  scaled by factor	m three cursor co with vertices A (2 r of 0.5 about a matrix and coord	0, 20), B (80, 20), and point X (40, 40). Det	C (20, 80) is to be ermine composite		<u>/</u> 4960
В)	5103617	Explain minimum A triangle ABC of scaled by factor transformation  Solve the follow	m three cursor co with vertices A (2 r of 0.5 about a matrix and coord ving.	0, 20), B (80, 20), and point X (40, 40). Det	C (20, 80) is to be ermine composite aled triangle.		5109647
B)	5103617	Explain minimum A triangle ABC vector scaled by factor transformation.  Solve the follow Compare the CS What are the variations.	m three cursor co with vertices A (2 r of 0.5 about a matrix and coord ving. G and B-Rep met rious windowing	0, 20), B (80, 20), and point X (40, 40). Det inates of vertices of scanning to the control of t	C (20, 80) is to be ermine composite aled triangle.	CO-02	696015
(Q.3	5103617	Explain minimum A triangle ABC vector scaled by factor transformation.  Solve the follow Compare the CS What are the variations.	m three cursor co with vertices A (2 r of 0.5 about a matrix and coord ving. G and B-Rep met	0, 20), B (80, 20), and point X (40, 40). Det inates of vertices of scanning to the control of t	C (20, 80) is to be ermine composite aled triangle.	CO-02	<b>12</b> 6 6
Q.3 A) B)	3 5103617	Explain minimum A triangle ABC of scaled by factor transformation.  Solve the follow Compare the CS What are the value of neat ske	m three cursor co with vertices A (2 r of 0.5 about a matrix and coord ving. G and B-Rep met rious windowing tches and suitabl	0, 20), B (80, 20), and point X (40, 40). Det inates of vertices of scanning to the control of t	C (20, 80) is to be ermine composite aled triangle.	CO-02	12 6 6
(Q.3	173     2103617	Explain minimum A triangle ABC of scaled by factor transformation  Solve the follow Compare the CS What are the variety of neat ske	m three cursor co with vertices A (2 r of 0.5 about a matrix and coord ving. G and B-Rep met rious windowing	0, 20), B (80, 20), and point X (40, 40). Det inates of vertices of scanning technology applications in CAD? E e examples.	C (20, 80) is to be ermine composite aled triangle.	CO-02	12 6 6 6
Q.3 A) B)	173     2103617	Explain minimum A triangle ABC of scaled by factor transformation  Solve the follow Compare the CS What are the variety of neat ske	m three cursor co with vertices A (2 r of 0.5 about a matrix and coord ving. G and B-Rep met rious windowing tches and suitabl	0, 20), B (80, 20), and point X (40, 40). Det inates of vertices of scanning technology applications in CAD? E e examples.	C (20, 80) is to be ermine composite aled triangle.	CO-02	12 6 6 6
Q.3 A) B)	3 5103617	Explain minimum A triangle ABC of scaled by factor transformation  Solve the follow Compare the CS What are the variety of neat ske	m three cursor co with vertices A (2 r of 0.5 about a matrix and coord ving. G and B-Rep met rious windowing tches and suitabl	0, 20), B (80, 20), and point X (40, 40). Det inates of vertices of scanning to the control of t	C (20, 80) is to be ermine composite aled triangle.	CO-02	12 6 6

A)		Write a manual part program for a plain and taper turning the forged bar	CO-05	6
		of 110 mm diameter as per the drawing shown.		
	1036173	Ø50		1036173
B)	5	Classify numerical control system based on	CO-05	16)
		1. Type of control systems		
		2. Type of motion control		
		3. Number of axes		
		Briefly discuss advantages and disadvantages of any one NC system.		
C)		What are the advantages of "Point to point control" in CNC systems? Also	CO-05	6
	73	mention in which particular applications it will be recommended?		23
	31			1
Q.5	6			in
	3	Solve Any Two of the following.		12
A)	103	Explain the terms:	CO-06	112 6
A)	5103	Explain the terms:  A. Field variables	CO-06	
A)	5103	Explain the terms:	CO-06	6
A) B)	5103	Explain the terms:  A. Field variables  B. Shape function	CO-06	6
	5103	Explain the terms:  A. Field variables  B. Shape function  C. Stiffness matrix		57
В)	5103	Explain the terms:  A. Field variables  B. Shape function  C. Stiffness matrix  Explain various properties of stiffness matrix	CO-06	6
В)	510	Explain the terms:  A. Field variables  B. Shape function  C. Stiffness matrix  Explain various properties of stiffness matrix	CO-06	6
B) C)	510	Explain the terms:  A. Field variables B. Shape function C. Stiffness matrix  Explain various properties of stiffness matrix  Explain various advantages of Finite Element Methods	CO-06	6
B) C) Q. (	510	Explain the terms:  A. Field variables B. Shape function C. Stiffness matrix  Explain various properties of stiffness matrix  Explain various advantages of Finite Element Methods  Solve Any Two of the following.	CO-06 CO-06	6 6
B) C) Q. (	510	Explain the terms:  A. Field variables B. Shape function C. Stiffness matrix  Explain various properties of stiffness matrix  Explain various advantages of Finite Element Methods  Solve Any Two of the following.  Discuss types of flexible manufacturing system layouts.	CO-06 CO-06	6 6 6
B) C) Q. ( A) B)	510	Explain the terms:  A. Field variables B. Shape function C. Stiffness matrix  Explain various properties of stiffness matrix  Explain various advantages of Finite Element Methods  Solve Any Two of the following.  Discuss types of flexible manufacturing system layouts.  What is computer integrated manufacturing (CIM)? List its benefits.	CO-06 CO-06 CO7 CO8	6 6 6 12